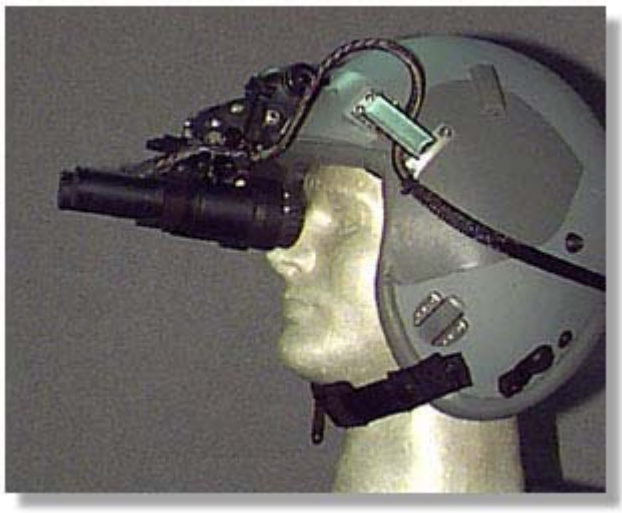
Night Vision Device (NVD) Training Research



NVTS Helmet-Mounted Display

The Night Vision Program of the Warfighter Readiness Research Division of the United States Air Force Research Laboratory (AFRL/HEA) was established to conduct research and development in support of the operational training requirements of aircrew using night vision devices, especially night vision goggles (NVGs). As part of an Advanced Technology Development project the “Fly by Night Training Team” has developed training materials, conducted instructor training, and provided technical support for operational units, flight test organizations, and acquisition programs.

Review and analysis of existing training systems identified a number of limitations inherent in existing NVG
simulations. AFRL/HEA, with input from operators and subject-matter experts, developed the Night Vision Training System (NVTS) in which a complete simulation approach has been developed. The goal of the NVTS program is to produce high fidelity, physics based, NVG simulation that will enable mission training, preview, and rehearsal whenever and wherever necessary. NVTS is a research and development effort and will transition to users.

NVTS uses a modular architecture in which the major components are; an image generator, an HMD, a NVG processor consisting of SensorHost software and an NVTS video-processing unit (NVP), and a head tracker. The SensorHost software runs on a PC and the NVP is a custom board. These components are government owned. The other components are COTS items. The goal is to be able to interface SensorHost and the NVP with a wide variety of systems.

The NVG imagery is based upon the modeling of the unique two dimensional NVG effects such as halos, gain response based on an accurate characterization of goggle sensitivity, gain, resolution, color, and field of view. The imagery is presented through a head tracked CRT-based display mounted in an actual NVG shell. This approach allows for the correct eyepoint for all crewmembers. Each display requires at least one channel of imagery. The three-dimensional world incorporates high resolution material-classified imagery, and accurate per-texel radiometric response of surface reflectance
and aspect. The current approach results in a single database which will support completely correlated visible and multiple sensor simulation. Current collaboration partners include the USN, USMC, USAF, AFRL/HEA, NAVAIR Patuxent River, NAVAIR Orlando, Aechelon Technology, SGB Enterprises, BTMD, SGI, 3D Pipeline, and CG2.

Features of the Current NVTS:

• Correlated photographic and material-classified database covers 380 nautical miles by 420 nautical miles of the Nellis training range. This database was derived from multispectral

satellite imagery, aerial photography, material spectral response data, and DTED elevation data. The database includes insets with submeter resolution imagery and full three-dimensional cultural feature extraction.
• The NVG sensor simulation uses a physics-based approach to provide an accurate NVG response to ambient illumination including gain response to in-band, radiometric response for reflectance and aspect of the material-coded texel under illumination. As the illumination level and angle change in the simulation, the amount of light reflected from each texel to the viewpoint changes in real time. Halos are simulated based on empirical data collected in laboratory and field data.
• Combat effects have recently been modeled and include several types of explosions, missile trails, flares and tracers. All of these effects include near- and in-view effects for haloing, gain, noise, and appearance.
• High-resolution helmet-mounted displays present the simulation to the user. These displays incorporate miniature cathode ray tubes (CRTs) mounted inside NVG shells to provide the same form, fit, and function of actual NVGs, with the same weight and center of gravity as the NVGs being modeled. The CRTs use the same phosphor as current NVGs in order to provide the same color and decay characteristics. Current HMDs have a display resolution up to 1700 pixels by 1350 lines, non-interlaced, refreshed at 60Hz.

Simulated NVG image

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